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COMMISSION OF THE EUROPEAN COMMUNITIES

AN INTERACTIVE SYSTEM FOR THE AUTOMATIC LAYOUT OF PRINTED CIRCUIT BOARDS (ARAIGNEE)

by

M. COMBET, J. EDER, C. PAGNY

1974



Joint Nuclear Research Centre Ispra Establishment — Italy

Technology Division

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Luxembourg, December 1974 - 34 Pages - 11 Figures - B.Fr. 120.—

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This procedure improves strongly the performance of the programme as far as the number of unresolved connections is concerned.

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ABSTRACT

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AN INTERACTIVE SYSTEM FOR THE AUTOMATIC LAYOUT OF PRINTED CIRCUIT BOARDS (ARAIGNEE)

1. INTRODUCTION

One of the most time consuming jobs during the production of printed circuit boards is the preparation of the artwork. The layout of a board of medium size requires days or even weeks of concentrated work of a skilled draftsman. Time delays caused by the layout work are the bottleneck during the development of any kind of digital circuits.

Computer aided design is a powerful tool for reducing such efforts. However, to be useful, the system must be designed with a feasible manmachine interface which permits a simplified communication between operator and computer.

Based on the UCARDS⁽¹⁾ code a software package has been prepared which in its first version presented here permits a certain degree of conversation, e.g. the operator may interrupt the automatic searching of paths between components at any step, he may insert a convenient correction by means of an adequate statement (see below) and then continue the operation. This procedure can improve strongly the performance of the programme as far as the number of unresolved path-connections is concerned.

An example given in this report shows that a number of 22 paths not found by the programme in one run, is reduced to 7 with only one manual intervention.

2. IMPROVEMENT OF THE UCARD'S PROGRAMME

The UCARD's programme - the only one available at Ispra - was developed in 1968. Therefore it does not contain in its component library complex elements like small and largescale integrated circuits etc. Furthermore, it does not respect modern circuit techniques like power supply busses and so on.

For these reasons a number of new commands have been inserted in the UCARD's vocabulary (it is supposed that the reader is familiar with the UCARD's language definition given in (1)):

INTEGRATED - insertion of integrated circuits described with a minimum number of parameters

BUS - insertion or deletion of paths with multiple connections

CALCOMP - programme interface to the CALCOMP-plotter

STOP - interruption of the programme execution after a prede-

fined path number.

For the ROUTER-routine a new algorithm is applied which searches and selects the shortest connections. A new procedure called DYNAMIC UP-DATING takes care of the handling of the STOP command, the updating and the correct restart of the programme.

In order to simplify the manipulation of data sets, the PSQ-facilities are used. A description of the control cards for the execution of ARAIGNEE and for the modification of the PSQ data sets will be given later on.

A number of errors found in the original UCARD's code have been

corrected, amongst them trivial errors like misprintings as XIØ against X10 and incompatibilities with library programmes. (IABS was replaced by LABS which calculates the absolute value for I±2 variables). A more serious error existed in the ORDER2-routine, where two statements (ORDE0046 and ORDE0055) were inverted).

In the COMPIL routine, the range of the pointer of the NSERT table was not limited, causing troubles with overflow.

3. SUBROUTINE ROUTER

The path-finding routine ROUTER is based now on an algorithm which is capable of doing the following:

- if more points have to be connected within one path, ROUTER calculates the distances and chooses the shortest path;
- every time a point must be connected with the I/O strip according to the "Arbitrary Nodes"-method, ROUTER selects the nearest point from the I/O strip;
- among all the connections "Arbitrary Nodes" to be realised, ROUTER selects the shortest first.

4. COMMAND STATEMENTS INTEGRATED, BUS

Format of the command:

INTEGRATED/name, $\left\{ \begin{smallmatrix} T \\ B \end{smallmatrix} \right\}$, name of nodes, I, J, IDISP, INC, JNC

where I, J are the coordinates of pin number 1

IDISP is a parameter defining one of four positions (see Fig. 1)

- = l pin l left side, up
- = 2 pin l left side, down
- = 3 pin l right side, down
- = 4 pin l right side, up

INC is the number of grid cells separating two adjacent pins (e.g. pin 1 and pin 2)

JNC is the number of grid cells separating two opposite pins (e.g. pin 1 and pin 14, resp. 16).

This statement which defines type and position of an integrated circuit is handled likewise as any other component descriptor.

- analysis of the statement's parameters,

The translating algorithm consists of two parts:

- calculation of all pin coordinates and insertion in the IDATA-vector of the general UCARD's component descriptor.

With the extensive use of integrated circuits a more convenient way to insert and delete paths became necessary than the commands INSERT PATH and DELETE PATH rendered possible. This will be shown in the following example:

The insertion of the path Nr. 64 represented in Fig. 2 requires the following UCARD command:

With the newly created BUS command all the redundant information may be omitted, thus

The improvement is obvious.

A further example concerning path Nr. 500, a typical line bus, is presented in Fig. 2:

BUS / T, 500, 20, 15, 17, 12, 13, 18, 10, 12, 7, 18, 3, 15, 5, 12, 1, 10, 5, 8, 1, 5, 3, 2, 5, 4, 8, 4, 8, 2

would be very difficult to translate into INSERT PATH statement. If the points are written in the right order (e.g. the points X, Y, Z, V must be written within A(20, 15) and B(3, 15)), all segments are automatically and correctly generated by the routine COMPIL.

The BUS command can be used for deleting a complex path, too. In this case the path to be deleted is described in the same way as shown above but the path number must be absent. (E.g. to delete path Nr. 64, write

5. DYNAMIC UPDATING

The UCARD system in its original version was conceived only for integral processing of layout jobs. No interaction during a run of the programme was possible.

With the introduction of integrated circuit packages this method showed serious drawbacks. As shown in Fig. 3, due to the in-line configuration of the IC-pins a path found by the UCARD strategy very easily surrounds a number of pins. Connections referring to these pins will be very difficult to realise and the probability of unresolvable connections will rise considerably. With the original UCARD procedure the only remedy was to delete those disturbing paths and insert others after the complete processing. In order to overcome these inconveniences, the dynamic updating was introduced. This method allows to stop the processing at any user-predefined level (path number), to correct the layout conveniently, deleting and inserting paths and to restart the programme from the point where it was interrupted. The programme interrupt may be provoked by the user with the command

where n is an integer number defining the path number at which the interrupt shall occur.

If n=0 only updating will occur (searching of new paths is inhibited).

The following example presents a typical sequence of commands for multiple programme interrupts: (see also Figs. 9 and 10)

```
circuit descriptors
FILE / 1
ROUTE /
STOP / 64
EXIT /
```

The process will stop when encountering path numbers $\stackrel{>}{=}$ 64. The actual information will be stored in FILE 1 and can be retrieved at restart with the statement SEARCH / file number. Updatings can now be executed e.g. with the commands:

```
SEARCH / 1

UPDATE /

BUS / (inserting or deleting paths)

INSERT HØLE / ...

DELET HØLE / ...

RESTART / 1

STØP / 75

EXIT /
```

The process is now interrupted at path number = 75 and may be restarted in the same manner. If no further interrupt is desired, the following sequence may be used to obtain a draft at the CALCOMP:

```
RESTART / 1
CALCØMP /
DRAFT /
EXIT /
```

6. PROGRAMME HANDLING BY MEANS OF PSQ

The manipulating of this 11000 cards containing programme is greatly facilitated by the use of the PSQ-system (see (2)).

For the normal execution of a layout job a standard deck with PSQ control cards has been prepared (Fig. 4). The user only has to insert the cards containing the parameters of its problem in the UCARD's language (see sample programme Figs. 9, 10).

A second deck of PSQ control cards is available for the case where temporary modifications of certain routines (in FORTRAN or in Assembler) are desired (Fig. 5). No permanent changement of the ARAIGNEE-code takes place.

If the ARAIGNEE data set has to be modified, the procedure shown in Fig. 6 can be applied.

7. SAMPLE PROGRAMME

Figs. 7 and 8 show the results for a practical layout problem, and Fig. 9 gives the respective input parameters.

Fig. 7 has been elaborated in one programme run without interventions by the operator. 17 connections could not be made by the programme.

Fig. 8 shows the same circuit. The programme was interrupted after path 69 and a correction of a number of connections was made (12 lines deleted and 14 new inserted, the parameter list for the corrections is given in Fig. 11).

After restart the programme was run without further interventions. Only 7 connections are still unresolved and have to be added by means of adequate statements.

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8. ANNEX

Flow charts concerning the modifications of the original UCARD routines are given in the annex.

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(1) J.F. JAMISON; "Union Carbide Automatic Routing and Design System for printed circuit boards", Union Carbide - Rep. Nr. K 1736 CTC-4

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(2) G. BUCCARI, C. DAOLIO, C. PIGNI, J. PIRE; "Sistema PSQ e file editor".

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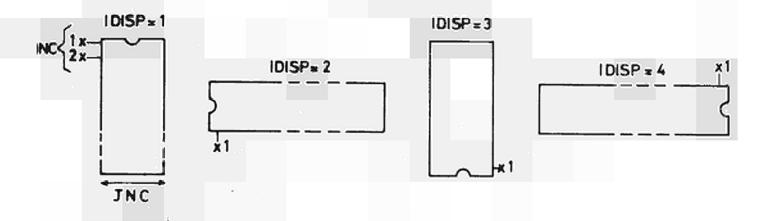


Fig. 1-ORIENTATION OF INTEGRATED CIRCUIT PACKAGES

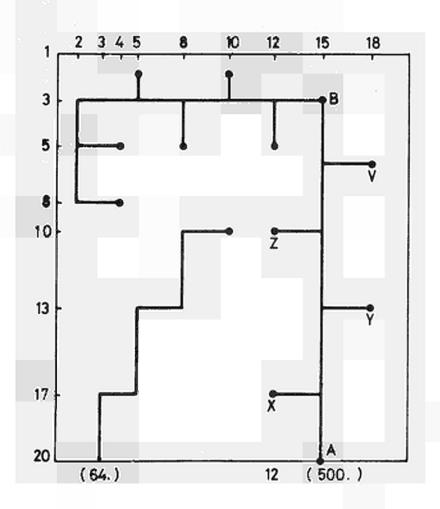


Fig. 2 - BUS CONNECTIONS

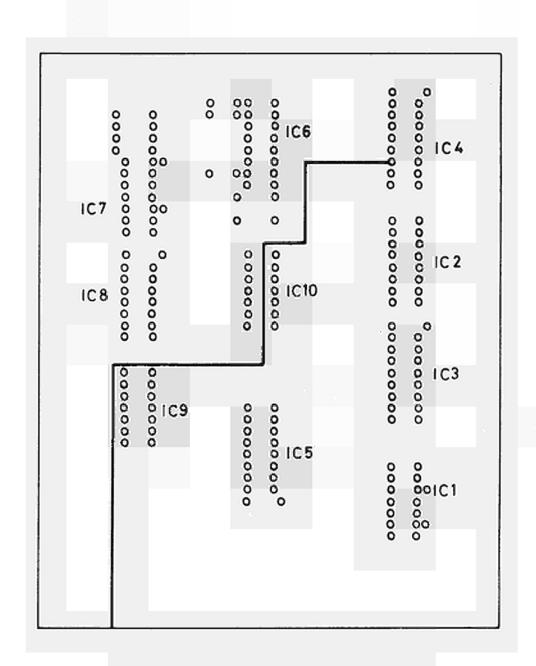


Fig. 3 - PATHS SURROUNDING IC-PINS

Fig. 4 - EXECUTION OF ARAIGNEE WITHOUT MODIFICATION

```
EXEC
              PSQ
// FTO2F001 DD UNIT=SYSSQ, DSN=&A, DISP=(NEW, PASS), DCB=(RECFM=FB,
         LRECL=80, BLKSIZE=800), SPACE=(CYL, (5, 1))
//GO.SYSIN DD ★
SOPEN, XXXXARAIGNEE
≴TO=02
$F
$E
/*
       EXEC FTLG, OV=OVLY
//LKED.SYSIN DD DSN=&A, DISP=(OLD, DELETE, DELETE), UNIT=SYSSQ
/★
//GO.FT17F001 DD UNIT=SYSSQ, DCB=(BLKSIZE=1200, RECFM=VS),
       SPACE=(CYL,(2,1))
    Same for FT17F002
                      FT17F003 FT17F004 .... FT17F012
                      FT42F001
    Same for FT40F001
                                 FT43F001 .... FT50F001
//GO.FT41F001 DD UNIT=3330, DSN=name of cylinder, VOL=SER=USER01,
       DISP=OLD
//GO.FT16F001
               DD DUMMY (IF CALCOMP is not requested)
//GO.SYSUDUMP DD SYSOUT=A
//GO. SYSIN
               DD *
    Programme statements
/≭
    If CALCOMP is requested, the DD cards definition must be:
//GO.FT16F001 DD UNIT=TP9, VOLUME=(PRIVATE, SER=EU3068),
//
           LABEL=(,,,OUT), DSNAME=Name,
           DCB=(RECFM=VS, BLKSIZE=488, LRECL=484, DEN=2)
```

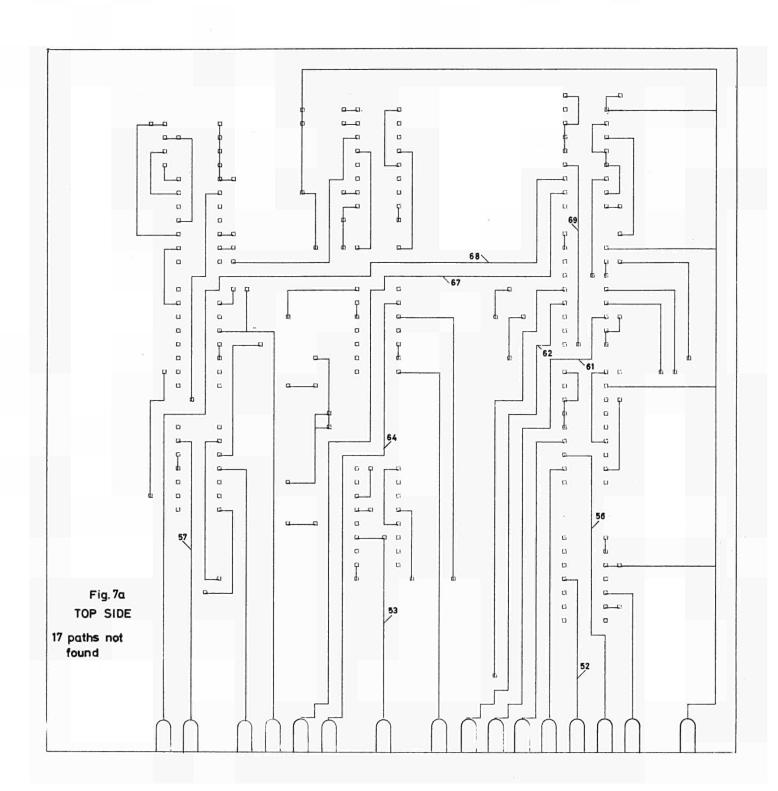
Programme size 300 Kbytes

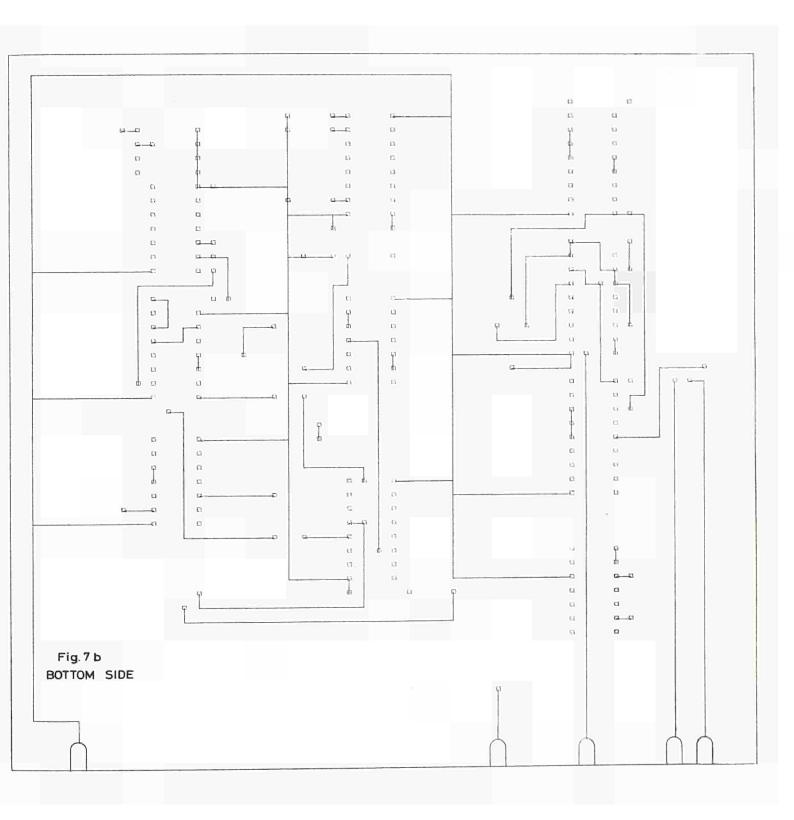
Fig. 5 - EXECUTION OF ARAIGNEE WITH TEMPORARY MODIFICATIONS OF ROUTINES WRITTEN IN FORTRAN AND/OR ASSEMBLER

```
EXEC
              PSQ
//FT02F001 DD UNIT=SYSSQ, DSN=&A, DISP=(NEW, PASS), DCB=(RECFM=FB,
         LRECL=80, BLKSIZE=800), SPACE=(CYL, (5, 1))
//GO.SYSIN DD *
SOPEN, XXXXARAIGNEE
$TO=02
$F
$E
/*
      EXEC
             FTGC
//CMP.SYSIN DD *
     Fortran routines
/눞
      EXEC AHC
//CMP.SYSGO DD DSN=&LOADSET, DISP=(MOD, PASS, DELETE),
      UNIT=SYSSQ, SPACE=(CYL, (3, 1), RLSE), DCB=(BLKSIZE=800)
//CMP.SYSIN DD *
     Assembler routines
/*
     EXEC FTLG, OV=OVLY
//LKED.SYSIN DD DSN=&LOADSET, DISP=(OLD, DELETE, DELETE),
//
     UNIT=SYSSQ
           DD DSN=&A, DISP=(OLD, DELETE, DELETE), UNIT=SYSSQ
            DD $ \ (Only if overlay is not on PSQ file)
        overlay
//GO.FT17F001 DD UNIT=SYSSQ, DCB=(BLKSIZE=1200, RECFM=VS),
      SPACE=(CYL,(2,1))
//
     The following cards are identical to the preceeding page
     Programme size 300 Kbytes
```

Fig. 6 - MODIFICATION OF THE ROUTINES OF A PSQ DATA SET COMPILATION AND CORRECTION OF BINARY DATA SET

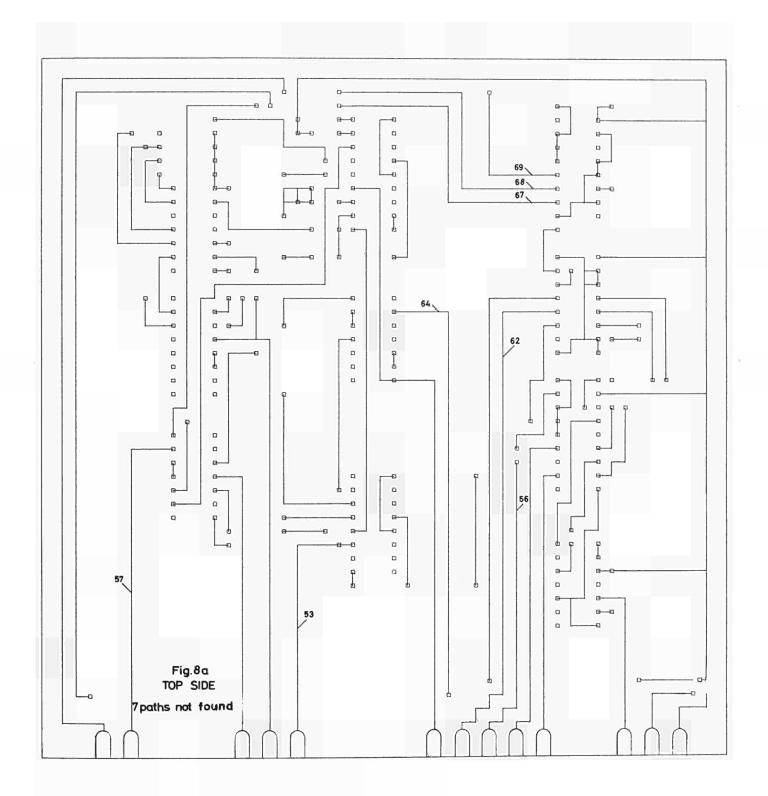
```
EXEC
           PSQ
//GO.FT01F001 DD DSN=&DSFOR, DISP=(NEW, PASS, DELETE), UNIT=SYSSQ,
    SPACE=(CYL, (1, 1)), DCB=(RECFM=FB, LRECL=80, BLKSIZE=800)
//GO.FT02F001 DD DSN=&DSASS, DISP=(NEW, PASS, DELETE), UNIT=SYSSQ,
    SPACE=(CYL, (1, 1)), DCB=(RECFM=FB, LRECL=80, BLKSIZE=800)
//GO.SYSIN DD *
                            SUPDATE, XXXXFORTRAN
SOPEN, XXXXFORTRAN
$TO=01
                            $TO=01
$F
                            $D,.....
$E
                              corrections
                            $F
                            $UPDATE, XXXXASSEMBL
SOPEN, XXXXASSEMBL
                            STO=02
$TO=02
                            $D,.....
$F
$E
                              corrections
                            $F
                            ŞΈ
/末
     EXEC FTGC
//CMP.SYSIN DD DSN=&DSFOR, DISP=(OLD, DELETE, DELETE), UNIT=SYSSQ
/宝
     EXEC AHC
//CMP.SYSGO DD DSN=&LOADSET, DISP=(MOD, PASS DELETE), UNIT=SYSSQ,
     SPACE=(CYL, (3, 1), RLSE), DCB=(BLKSIZE=800)
//CMP.SYSIN DD DSN=&DSASS, DISP=(OLD, DELETE, DELETE), UNIT=SYSSQ
/宝
     EXEC
            PSQ
//GO.FT02F001 DD DSN=&LOADSET, DISP=(OLD, DELETE, DELETE),
     UNIT=SYSSQ, DCB=(RECFM=FB, LRECL=80, BLKSIZE=800)
//GO.SYSIN DD *
SGENERATE, XXXXARAIGNEE
                            $UPDATE, XXXXARAIGNEE
                            $PY
$PY
                            $TI=03
$TI=03
$F
                            $F
                              overlay
     overlay
$E
                            $E
/*
                            /*
```

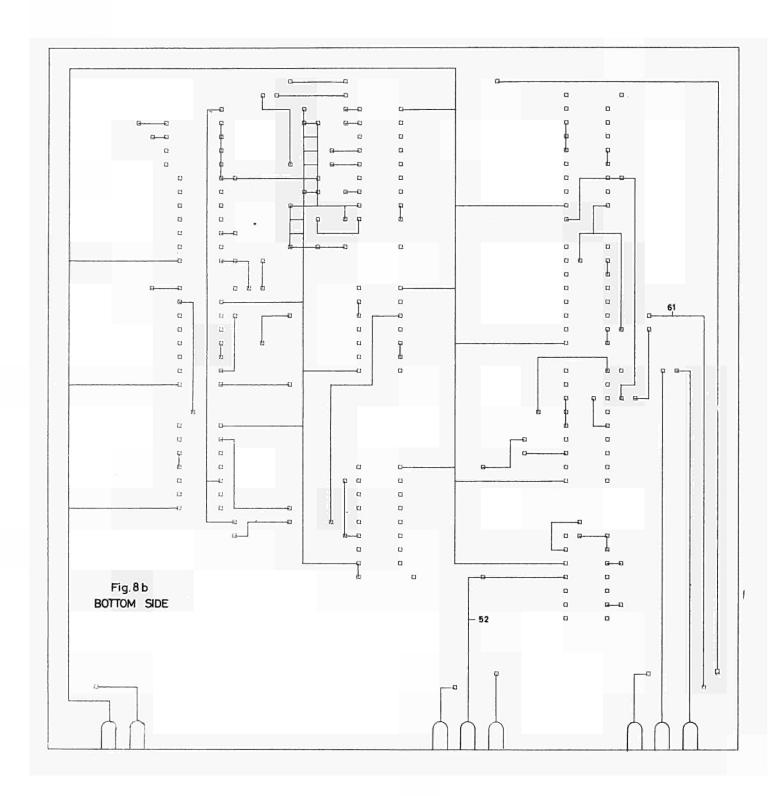




THE FULLOWING			CONNECTIONS COULD			NOT BE MADE			
101	1	TO	ICl	12			н	vET=	0.0TNET=10.0
101	12	TO	IC3	9			н	VE T=	0.01NET=10.0
101	7	τo	ICI	10			н	NET=	0.0TNET=10.0
101	8	TO	103	14			н	NET=	0.0TNET=10.0
IC1	9	TO	103	11			н	VE T=	0.0TNET=10.0
ICI	11	TO	IСЗ	1			H	VET=	0.0TNET=10.0
IC2	6	TO	IC3	13			: H1	NET=	0.0TNET=10.0
IC2	7	TO	IC3	15			н	NE T=	0.01NET=10.0
1C3	15	TO	IC4	1			Н1	NET=	0.01NET=10.0
103	16	TO	R2	2			н	VE T=	0.0TNET=10.0
IC4	8	TO	IC4	10			н	NET=	0.01NET=10.0
106	13	TO	IC9	1			н	NET=	0.0TNET=10.0
IC6	14	TO	1010	1			11	NET=	0.0TNET=10.0
IC8	1	TO	IC9	5			H	NET=	0.0TNET=10.0
107	8	Tυ	IC8	9			н	NET=	0.01NET=10.0
IC7	- 12	TO	IC9	2			н	NET=	0.0TNET=10.0
IC9	9	TO	IC10	4			H	VET=	0.0TNET=10.0

Fig.7c





THE	FOLLOWING		CONNECTIONS		COULD NOT BE MADE
103	13	TO	IC4	14	HNET= 0. OTNET=10.0
IC2	7	TO	1C3	15	HNET= 0.0TNFT=10.0
IC3	15	TO	IC4	1	HNET= 0-0TNET=13-0
103	16	TO	R2	2	HNST= 0: OTNET=10:0
107	12	TO	IC9	2	HNET= 0, OTNET=10.0
108	3	TO	IC8	13	HNET= 0.0TNET=10.0
109	9	TO	1010	4	HNET= 0.0TNET=13.0

Fig.8c

```
TITLE/
                    INTEGRATED CIRCUITS
 FILE / 1
 GRID SIZE/50,50
 CELL SIZE/. 1
10 HEIGHT/. 1
 FPAME /50., 0., 0., 0., 51., 50., 51.

IC STRIP/1.5, 1.5, 2, 1., 22

FAILURE LIMIT/99

SCALE/0.5
  PUNCH DPT ION/OFF
 PREDEFINE!
 BUS/B, 500, 50, 5, 48, 5, 48, 2, 34, 9, 25, 9, 16, 9, 2, 2, 2, 30, 5, 27, 12, 37, 18, 27, 22, 37, 31, 27, 32, 37, 38, 37, 38, 30

BUS/T, 501, 50, 47, 48, 47, 48, 49, 38, 43, 25, 42, 15, 42, 5, 42, 2, 49, 2, 19, 5, 19

BUS/B, 501, 5, 19, 10, 14, 12, 22, 19, 14, 24, 22, 28, 14, 38, 22, 38, 19

ARBITRARYNDD/3, 9, 11, 12, 13, 16, 17, 23, 24, 25, 37, 48, 60, 58, 71, 74, 30, 31, 32
                                                                                                                                                  CONT
DEFINE/
CNE SIDED
                                                                                                                                                  CONT
                                                                                                                                                  CONT
                                                                                                                                                  TYCO
 RESISTOR/R13, T, 54, 61, 6, 9, 6, 13
PESISTOR/P14, T, 59, 61, 14, 14, 10, 14
 RESISTOR/RI5, T, 60, 50, 13, 26, 13, 22
  ROUTE/
  DRAFT/
  STOP/69
  EXIT /
                                       Fig. 9-INPUT PARAMETERS FOR SAMBLE LAYOOT
```

```
UPDATE/
   BUS/T, 39, 39, 50, 39
BUS/T, 36, 23, 36, 25, 50, 25
BUS/T, 30, 39, 30, 40, 43, 40, 43, 41, 50, 41
BUS/1, 30, 39, 30, 40, 43, 40, 43, 40, 43, 41, 30, 41, 30, 41, 80, 41, 29, 10, 29, 11, 50, 11

BUS/T, 29, 10, 29, 11, 50, 11

BUS/T, 20, 40, 23, 40, 23, 37, 28, 37, 28, 35, 48, 35, 48, 34, 49, 34, 49, 33, 50, 33

BUS/T, 19, 37, 22, 37, 22, 36, 27, 36, 27, 34

BUS/T, 19, 25, 30, 25, 30, 22, 49, 21, 49, 21, 50, 21

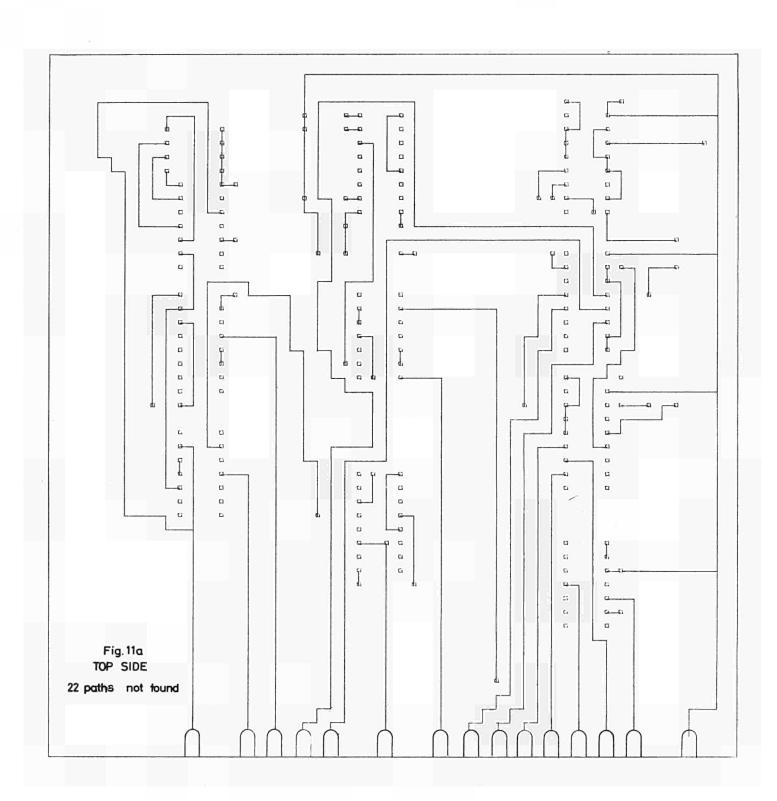
BUS/T, 18, 38, 18, 36, 21, 36, 21, 35, 26, 35, 26, 33

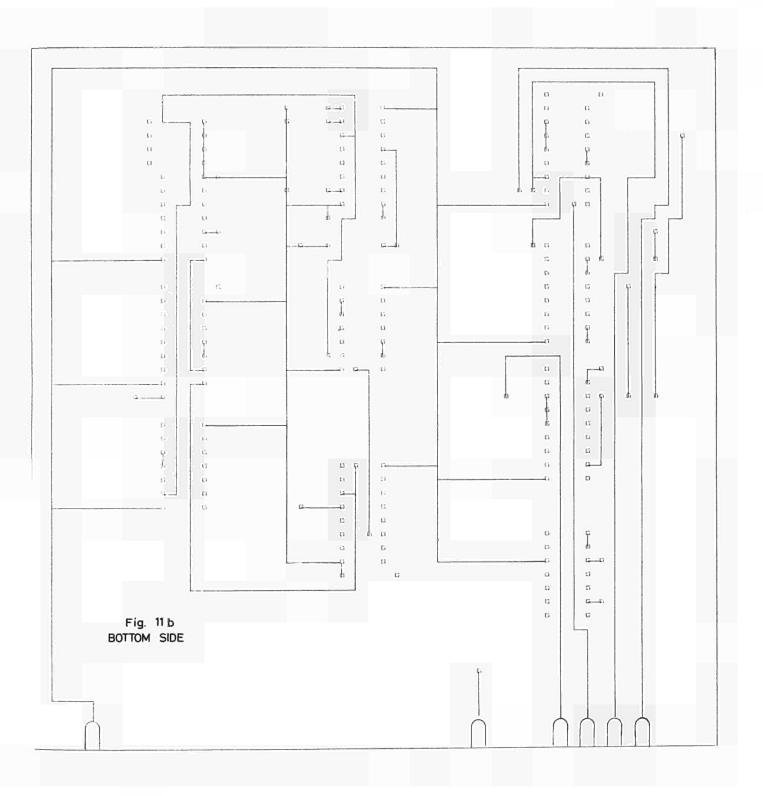
BUS/T, 11, 37, 17, 37, 17, 25, 18, 25, 18, 24, 29, 24, 29, 21, 48, 21, 48, 20, 49, 20, 49, 19, 50, 19
                                                                                                                                                                                                                                                                                                                                                                                                                 TVCS
BUS/T,11,37,17,37,17,25,18,25,18,24,29,24,29,21,48,21,48,20,49,20,49,150,19
BUS/T,10,38,10,36,16,36,16,24,17,24,17,13,18,13,18,12,27,12,27,9,50,9
BUS/B,22,39,50,39
BUS/B,22,39,50,39
BUS/B,52c,39,38,39,31,50,31
BUS/T,53c,36,38,30,35
BUS/T,55c,30,35,48,35,48,34,49,34,49,33,50,33
BUS/T,56c,30,35,48,35,48,34,49,34,49,33,50,33
BUS/T,56c,20,41,20,44
BUS/B,66lc,20,44,20,44
BUS/B,66lc,20,44,20,44
BUS/B,66lc,20,44,20,44
BUS/T,66c,10,37,19,34,30,34
BUS/T,66c,10,37,19,34,30,34
BUS/T,67c,11,38,11,30,4,30,4,22
BUS/T,67c,41,17,38,11,30,4,30,4,22
BUS/T,67c,41,17,38,11,30,4,30,4,22
BUS/B,67c,47,22,4,17
BUS/B,67c,47,40,47,70,50,7
BUS/B,67c,47,40,47,70,50,7
BUS/T,68c,10,38,10,31,3,31,3,22
BUS/T,68c,10,38,10,31,3,31,3,22
BUS/T,68c,3,18,2,18,2,2,49,2,49,5,50,5
BUS/T,68c,3,18,2,18,2,2,49,2,49,5,50,5
    BUS/T, 69.; 9, 38, 9, 33, 3, 33
BUS/B, 69.; 3, 33, 3, 49, 46, 49
BUS/T, 69., 46, 49, 46, 44
   BUS/B, 69, 46, 46, 46, 43, 50, 43

DELETE HOLE/22, 39

INSERTHOLE/30, 35, 20, 44, 47, 48, 47, 30, 4, 22, 4, 17, 47, 4, 3, 22, 3, 18, 3, 33, 46, 49, 46, 44
    RESTART/1
    DRAFT /
     EXIT /
```

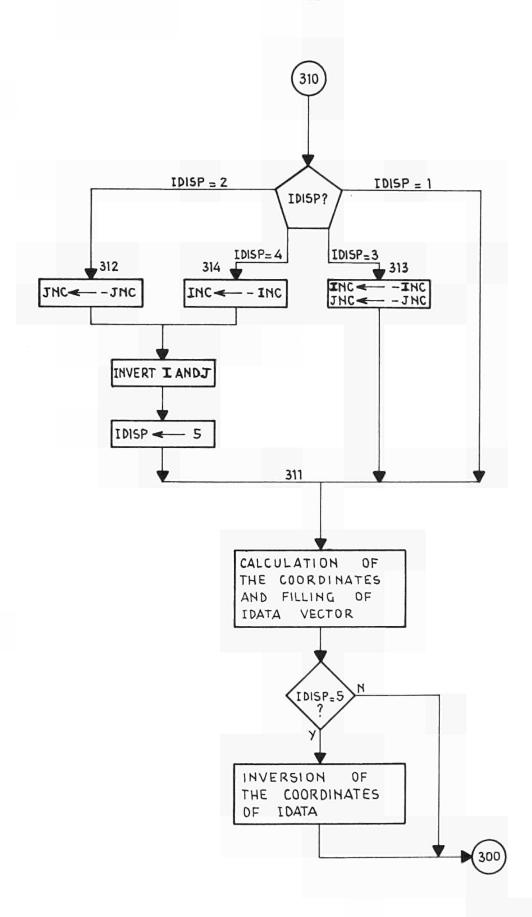
Fig. 10 UPDATED PARAMETERS



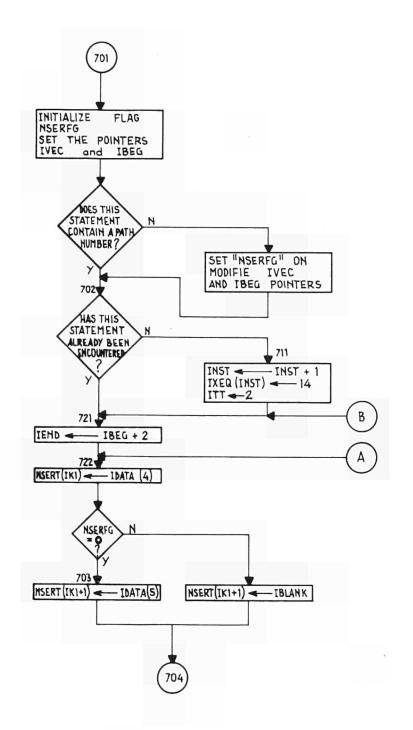


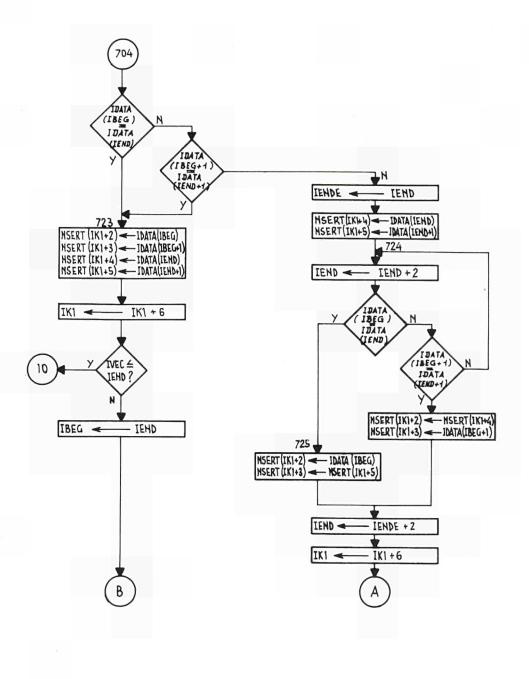
THE	FOLLOW:	NG	CONN	ECTIONS	COULD	NOT BE	BCAM		
ICI	1	TO	101	12		HN=T=	O. OTNET	=10.0	
101	.12	TO	103	9.		HNET=	O. OTNET	0 7 C 1=	
ICI	7	TO	ICl	10		HNET=	O, OTNET	=10.0	
101	8	TO	103	14		HNET=	O, OTNET	=10.0	
101	9	TC	IC3	11		HNET=	0. OTNET	=1 0 c 0	
ICl	11	TO	103	1		HNET=	O. OTNET	=1 3 c 0	
102	1	TO	102	15		HNET=	O. OTNET	=100	
102	9	TO	102	8		HNE T=	0. OTNET	=10:0	
102	3	TO	IC4	9		HNET=	O. OTNET	=10.0	
102	6	TO	103	13		HNE T=	O. OTNET	=10 - 0	
IC2	7	TO	IC3	15		HNET=	0. OTNET	=10:0	
103	15	TO	104	1		HNET=	O. OTNET	=1 0 c 0	
104	8	TC	104	10		HNE T=	O, OTNET	=1 0 0	
105	13	TO	107	13		HNET=	O. OTNET	=10.0	
106	12	TO	109	10		HNET=	O. OTNET	=10 _e 3	
106	13	TO	109	1		HNET=	O. OTNET	=10.0	
106	14	TO	1010	1		HNE T=	O. OTNET	=1.0 c 0	
IC7	9	ΤC	108	12		HNET=	O. OTNET	=10 _c 0	
IC8	3	TO	108	13		HN∈T=	O. OTNET	=10.0	
109	8	TO	1010	5		HNET=	O, OTNET	=1 0 c 0	
109	9	TO	1010	4		HNE T=	O. OTNET	=10:0	
IC9	12	TO	1010	8		HNE T=	O, OTNET	=10.0	

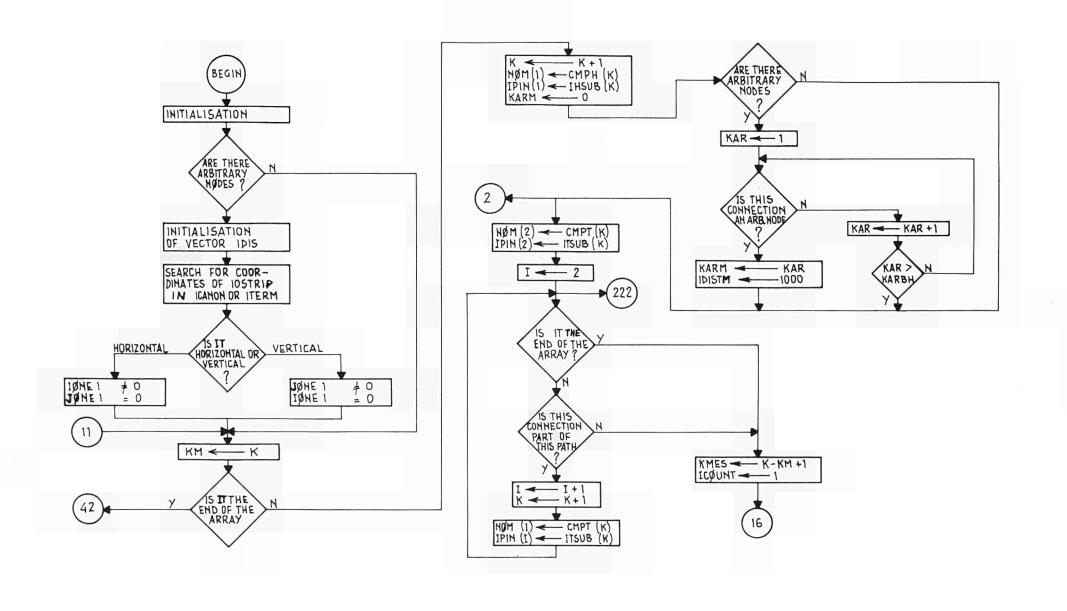
Fig. 11 c



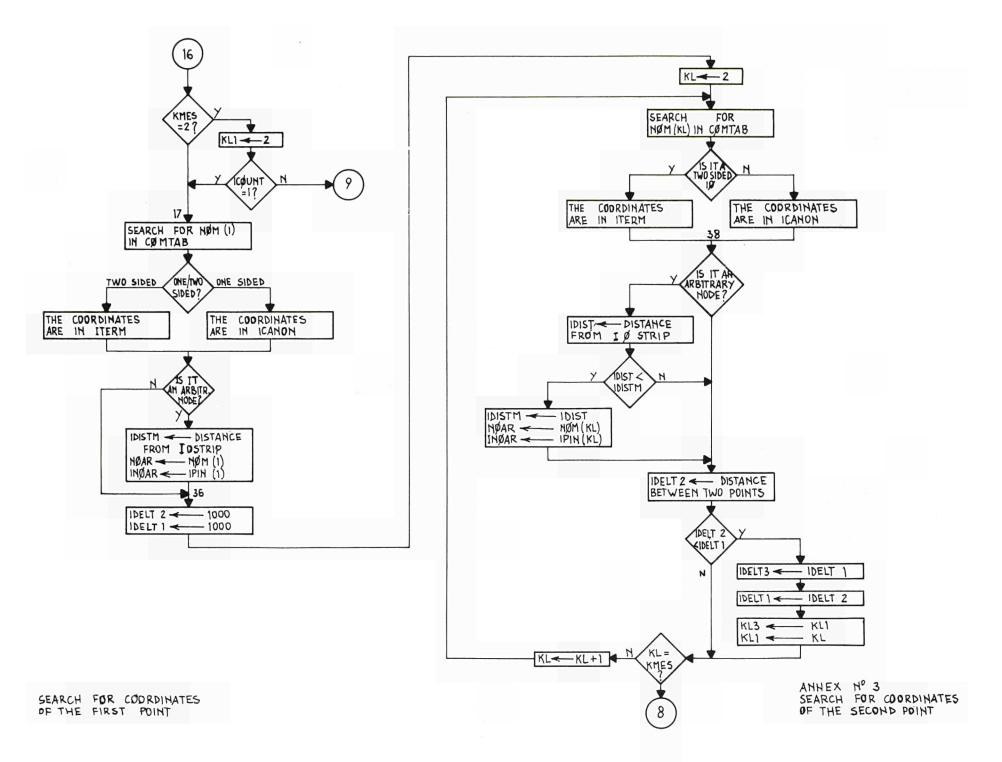
ANNEX N° 1 CØMPIL STATEMENT INTEGRATED/

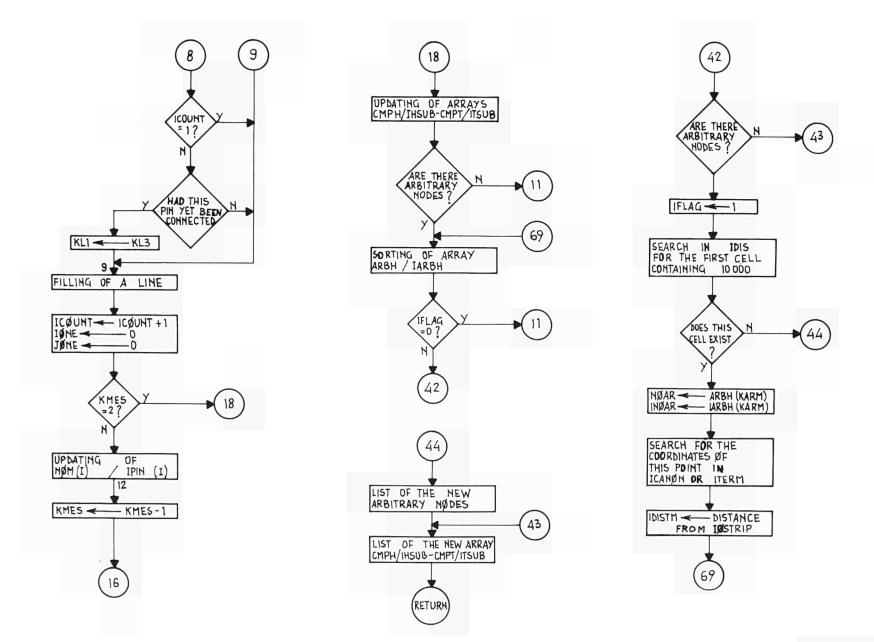






ANNEX N° 3
SEARCH FOR ARBYTRARY NODES AND
BEGIN TO FILL NOM (I)
IPIN (I)





ANNEX N° 3 FILLING OF THE ARRAYS TH/ITH - TT/ITT

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